# Precision Race Services Inc. Is your OBR North American Dealer











| Generic OBR Control Systems Inc Engine Management Systems  |                              |                            |                          |  |  |
|--|------------------------------|----------------------------|--------------------------|--|--|
|  | Euro-4                       | Euro-8                     | Euro-5                   |  |  |
| Control Systems  |                              |                            |                          |  |  |
| Hardware Control of the Control of t |                              |                            |                          |  |  |
| Injection Drivers On-Off / max optional / Peak&Hold  | 8 / 8 / No                   | 8 / 16 / No                | 4 / 4 / Yes              |  |  |
| DI drivers (configurable boot voltage / current profile)   | Via external module          | Via external module        | 4 / Yes / Yes            |  |  |
| Programmable firing order    Ignition Drivers  | Yes                          | Yes                        | Yes                      |  |  |
| Internal power stage   | 4                            | 8                          | 4                        |  |  |
| Logic level driven (coil integrated power stage) Programmable firing order   | 4<br>Yes                     | 8<br>Yes                   | 4<br>Yes                 |  |  |
| Trigger / Speed / Position   | les                          | 163                        | res                      |  |  |
| Hall effect (DHE)  Variable reluctance (VRS)   | 4 (hardware)<br>4 (hardware) | 4                          | 4                        |  |  |
| Custom configurable trigger patterns   | Yes                          | Yes                        | Yes                      |  |  |
| Max Number of Engine Cylinders   |                              |                            | <u>.</u>                 |  |  |
| Full sequential / semi sequential  General I/O   | 4/8                          | 8 / 12                     | 4                        |  |  |
| Analogue inputs  | 15                           | 15                         | 15                       |  |  |
| Digital inputs (total excl DHE) PWM  | 7                            | 13<br>13                   | 11<br>11                 |  |  |
| Digital outputs (total)  | 8                            | 20                         | 17                       |  |  |
| PWM  | 4                            | 16                         | 13                       |  |  |
| H-bridge drivers (full bridge) Half bridge drivers   | 1 -                          | 2                          | 2                        |  |  |
| Stepper motor  | 1                            | (using full bridge)        | (using full bridge)      |  |  |
| DI pump driver<br>Import data via SENT protocol  | Via external module          | Via external module<br>Yes | 1<br>Yes                 |  |  |
| Dedicated I/O  | -                            | res                        | res                      |  |  |
| Wide band lambda (UEGO) input/CAN  | 1 / +3 via CAN               | 2 / +8 via CAN             | 1 / +3 via CAN           |  |  |
| Lambda control using wide band sensor<br>Lambda self mapping using wide band sensor  | Yes<br>Yes                   | Yes<br>Yes                 | Yes<br>Yes               |  |  |
| Knock sensor input   | 2                            | 2                          | 2                        |  |  |
| Thermocouple (K-type) Resistance temperature sensors (NTC)   | Via external module<br>4     | Via external module<br>5   | Via external module<br>5 |  |  |
| Internal Data Logger   | 4                            | •                          | 3                        |  |  |
| Memory   | 8 Mb                         | 128 Mb                     | 128 Mb                   |  |  |
| Maximum logging rate Hz Maximum logging channels   | 200<br>32                    | 200<br>64                  | 200<br>64                |  |  |
| Analysis software Stack / 2D   | Yes                          | Yes                        | Yes                      |  |  |
| Track mapping  General   | Yes                          | Yes                        | Yes                      |  |  |
| I/O expandable via CAN   | Yes                          | Yes                        | Yes                      |  |  |
| Stand alone capability / Full access   | Yes/Yes                      | Yes/Yes                    | Yes/Yes                  |  |  |
| Compact design / portable  Interfaces  | Yes                          | Yes                        | Yes                      |  |  |
| CAN  | 2                            | 3                          | 3                        |  |  |
| Import data via CAN Export data via CAN  | Yes<br>Yes                   | Yes<br>Yes                 | Yes<br>Yes               |  |  |
| ASAM MCD3 (ASAP3)  | Yes                          | Yes                        | Yes                      |  |  |
| Ethernet   |                              | 1                          | 1                        |  |  |
| Software Application system  | own                          | own (others on request)    | own (others on request)  |  |  |
| Custom configurable control strategy   | (sup)                        | (sup)                      | (sup)                    |  |  |
| Generic gasoline control strategy available Required software  | Yes<br>ECT DN                | Yes<br>ECT DN              | Yes<br>ECT DN            |  |  |
| Annual software license fee  | No                           | No                         | No                       |  |  |
| Communication PC<->ECU   | CAN                          | CAN / Ethernet             | CAN / Ethernet           |  |  |
| Advanced Software Strategies Alternator control  | Yes                          | Yes                        | -                        |  |  |
| Boost control - closed loop with solenoid / DC motor   | Yes / Yes                    | Yes / Yes                  | Yes / Yes                |  |  |
| Boost control - anti turbo lag control  Drive by wire control  | Yes<br>1                     | Yes<br>2                   | Yes 1                    |  |  |
| Fan control  | Yes                          | Yes                        | Yes                      |  |  |
| Gear shift - full throttle shift strategy  | Yes                          | Yes                        | Yes                      |  |  |
| Gear shift - semi automatic paddle shift<br>Gear shift - gear detection / gear engaged   | Yes<br>Yes                   | Yes<br>Yes                 | Yes<br>Yes               |  |  |
| Knock control  | Yes                          | Yes                        | Yes                      |  |  |
| Lambda fuel control and self mapping  Launch control   | Yes<br>Yes                   | Yes<br>Yes                 | Yes<br>Yes               |  |  |
| Pit speed mode   | Yes                          | Yes                        | Yes                      |  |  |
| Programmable RPM limiter   | Yes                          | Yes                        | Yes                      |  |  |
| Programmable RPM limiter conditions  Quick start strategy  | Yes<br>Yes                   | Yes<br>Yes                 | Yes<br>Yes               |  |  |
| Traction control   | Yes                          | Yes                        | Yes                      |  |  |
| Variable camshaft timing, up to 4 cams  Notes  | Yes                          | Yes                        | Yes                      |  |  |
| Full access to all software features incl logger   | Yes                          | Yes                        | Yes                      |  |  |
| (sup)  |                              | Support from OBR           | Support from OBR         |  |  |



# **EURO-4 ECU**

## Much more than just an engine management system....

Euro-4 is the latest generation engine management system from OBR Control Systems. It is one of the smallest and yet one of the most powerful ECU's for use on engines with up to 8 cylinders. Based on a modern production car ECU, Euro-4 is built to conform to the latest high automotive technology standards. The ECU is designed to form the centre of an integrated electronic system in a modern racing car and offers an extraordinary high level of features at an attractive price.

The price of the ECU includes full-option software specifications. All features and strategies are available to the user at no extra cost.

### Features

Euro-4 can control normally aspirated, turbo charged and super charged engines. Additionally, the ECU can control a drive-by-wire operated throttle body, including safety features recognised from production cars.

It has built-in ignition drivers for both inductive and logically operated ignition coils and can control engines with up to 8 cylinders in full sequential fuel injection – or using staged injection in 4-cylinder mode.

It accepts up to 4 crankshaft and camshaft sensors, being either inductive or Hall effect. The ECU can control many bespoke variable camshaft timing systems found on modern engines.

Euro-4 has a total of 22 analogue and 13 digital sensor inputs. The advanced software allows the user to configure the ECU to accept inputs from many different sensors.

Euro-4 is also capable of running Direct Injection gasoline engines. DI software strategies allow control of both Bosch & Hitachi high pressure pumps with GM Ecotec & VW TFSI engine types software selectable. Other DI engine types will require scope traces of Crank, Cam & pump lobes to be submitted.





### System Overview

- PowerPC microprocessor
- Up to 4 cylinders in full sequential mode;
- 6 and 8 cylinders in full sequential injection and wasted spark mode
- Ignition coil drivers for both inductive and logic operated coils, including plug-top coils
- Drive-by-Wire throttle PID control
- · On-board data logging with 8 Mb memory
- Automatic fuel mapping
- Closed loop lambda control
- Closed loop boost control
- · Variable camshaft timing with PID control strategy
- · Idle speed control
- · 2 selectable engine maps
- Control of direct injection engines with Hitachi and Bosch HDP5 fuel pumps.

### General

- · Very small and flat die cast aluminium enclosure
- 2 automotive main connectors with high pin density; 96 pins in total
- Dimensions 165 x 95 x 21 mm
- Weight 386 Grams

### Inputs

- 4 inductive or Hall effect engine speed and synchronisation sensor inputs
- · 4 Hall effect wheel speed sensors
- · 3 spare Hall effect / digital switch inputs
- 2 knock sensor inputs
- 1 direct NTK UEGO lambda sensor input
- 20 analogue 0..5 Volts external sensor inputs (can also be used as switch inputs)
- 1 built-in barometric air pressure sensor
- 8 spare analogue sensor inputs via CAN
- 4 Hall effect wheel speed sensors

### Communication

- 2 x CAN 2.0B interfaces
- Standard EFI Technology or user defined CANdata export and import
- 16 CAN identifiers available for data export
- 2 CAN identifiers available for data import

### Outputs

- 8 on-off fuel injector drivers
- 4 inductive ignition coil drivers
- 4 logic ignition coil drivers
- 8 multipurpose switches and PWM's
- 1 lambda sensor heater
- 1 H-bridge drive-by-wire throttle controller
- 1 four-phase stepper motor drive
- 4 independent 5.0 V sensor power supplies

### Special Feature

- Up to 4 wide band sensors can be used for closed loop fuel control
- Special engine type configurations including several motorcycle engines
- · Control strategy for paddle shift and air compressor
- · Control strategy for sequential gear change
- Traction control with target slip map
- Pit lane, launch and adjustable manual limiter
- · Programmable firing order
- Comprehensive CAN features
- Special version available with fully encrypted software
- · Special version homologated for use in \$2000 rally cars
- · Special version homologated for use in world touring cars

### Conditions for use

- Temperature range -40...+125 degrees C
- Power supply 7..16 volts





Euro-5 is a brand new, all-in-one ECU developed predominantly for use on 4-cylinder direct injection engines. The Euro-5 ECU has 4 on-board direct injection driver stages plus 4 additional injector drivers for combined port/direct fuel injection applications. The intuitive software allows for full programmability of injector voltages, current settings, plus current control of the high pressure fuel spill valve providing ultimate flexibility. Euro-5 can handle direct injection engines that feature either Bosch or Hitachi high pressure fuel pumps, driven off a camshaft with up to 4 pump lobes.

All our ECU's for motorsport are derived from OEM road car systems. This ensures they are built to the highest specifications required by today's high tech automotive industry. The knock on effect also means that the software strategies for drive-by-wire, variable camshaft timing, knock control, direct fuel injection and high pressure fuel control continuously deliver accurate and reliable functionality.

OBR's first installation on a direct fuel injection engine was almost 20 years ago. Ever since we have been supplying systems for direct injection engines within the automotive development, durability and testing sectors alongside on track motorsport activities.

Euro-5 features sync-less quick start from 1 or 2 crankshaft speed sensors. Cam and crank sensors can be VR or Hall effect type sensors and can support and control most types of modern ignition coils. Almost all standard OEM crank trigger patterns are supported, including the most common 60-2 tooth arrangement.

Furthermore, with its 128Mb on-board data logger memory capacity and 64 logged channel upper limit, it makes the Euro5 ECU one of the most versatile and robust aftermarket engine management solutions for direct injection racing engines available.

Special software/hardware encrypted versions are available. These can limit functionality and offer security to give total peace of mind for not only Championship organisers but other competitors as well.

### APPLICATION

Processor type
Engine Layout
Engine Type
Control Strategy
Injector Drivers

PowerPC family
4 cylinder N/A or turbo charged
Direct injection + Port injection
MAF, MAP or TPS
4 x DI and 4 x port

Injector Drivers 4 x DI and 4 x port
Ignition Drivers 4 x power drivers plus 4 x logic drivers
Fuel Pump Control Bosch or Hitachi

Lambda Sensor
Knock Control
Firing Order
Data Exchange

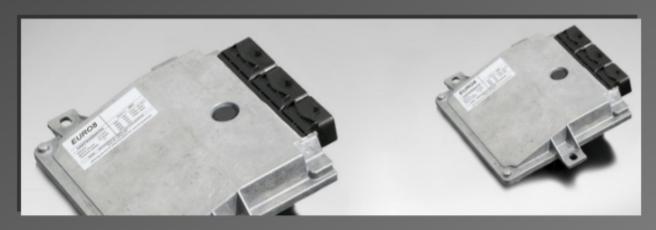
Bosch of Hirach
1 x NTK UEGO
2 channels
Programmable
3 x CAN ports

Communication CAN plus 10/100 Mbit/s Ethernet Data Logging On-board 128 Mb

Data Logging On-board 128
Dimensions (mm) 177 x 165 x 36
Weight 825 grams

### Features

- · ASAP3 link and boost control with anti-lag
- · Bosch and Hitachi pump control
- Programming of injector voltage and current levels
- · Closed loop and self-learn lambda control
- · Data import from Bosch and Teves ABS
- · Drive-by-wire throttle control
- · Gear dependent traction control with PID regulation
- . Knock control with 1 or 2 sensors
- Max RPM >15,000 RPM in DI mode
- Paddle shift control strategy
- Variable camshaft timing
   VTEC for Honda engines
- 1 built-in barometric sensor
- 2 extra half bridge drivers
- 2 extra nait briage arivers
- · 2 selectable crankshaft sensor inputs
- 5 selectable engine maps
- 19 digital sensor inputs (plus an additional 17 spare)
- 19 analogue sensor inputs





# **EURO-8 ECU**

### The Next Generation Engine Management System.

Euro-8 is the latest generation engine management system from OBR Control Systems. It is one of the smallest and yet one of the most powerful ECU's specially developed for use on 6, 8, 10 and 12 cylinder engines.

Based on a modern Power-PC processor, Euro-8 is built to conform to the latest high automotive technology standards.

The ECU is designed to form the centre of an integrated electronic system in a modern racing car and offers an extraordinary high level of features at an attractive price.

The price of the ECU includes full-option software specifications.

All features and strategies are available to the user at no extra cost.

### Features

Euro-8 can control normally aspirated, turbo charged and super charged engines, including controlling stategies for direct injection engines. Engine load can be expressed as manifold air pressure, mass air flow or throttle position. Additionally, the ECU can control two drive-by-wire operated throttle bodies, including safety features recognised from production cars.

Having 8 built-in ignition drivers for plug top logically operated ignition coils and 8 injector drivers it can control engines with up to 8 cylinders in full sequential mode. 10 and 12 cylinder engines are controlled having full sequential injection and wasted spark ignition mode.

It has inputs for 2 crankshaft speed sensors and up to 4 camshaft sensors, being either inductive or Hall effect.

The ECU can control many bespoke variable camshaft timing systems found on modern engines.

Euro-8 has a total of 42 analogue and digital sensor inputs. The advanced software allows the user to configure the ECU to accept inputs from many different sensors.

### **Data Recording**

Data can be recorded using Euro-8's internal 16 Mb internal data logger. As well as ECU and sensor data channels, Euro-8 can record data from other systems, such as external CAN modules, the OBR PCM and membrane switch panel. Data is downloaded via the ECU's Ethernet link.

### **CAN Communication**

Its extensive CAN (Controller Area Network) capabilities, having 3 individual CAN ports, ensures a simplified electrical installation combined with very advanced features. The data export includes a user-defined CAN configuration with 16 available CAN identifiers.

Data from 8 additional sensors and commands from other CAN bus systems in the car can be imported via CAN.

### Special Features

The ECU comes with a software package including advanced features, for example:

- Gear dependent traction control using target slip Maps with user controls.
- Programmable flat shift strategy.
- Paddle shift and air compressor control.
- Dual channel knock control.
- Inputs for 2 NTK calibrated wide band lambda sensors.
- Driver adjustable launch control.
- Intelligent closed loop lambda fuel control.
- · Variable camshaft timing.
- 6 selectable engine maps.
- Dual drive-by-wire throttle body control.
- 2 spare half bridge drivers.
- Programmable RPM limiter cut patterns.
- Control of direct injection engines with Hitachi and Bosch HDP5 fuel pumps.
- Available with fully encrypted software.

| neric OBR Control Systems Inc Power Control Systems  |   |   |   |   |  |
|--|---|---|---|---|--|
| roduct<br>tatus  | PCM AC<br>Active                              | PCM LITE Active                               | PCM2-34 Active                                | PCM2-48<br>Active                             |  |
|  | Data  |   | 2000  | 2000  |  |
|  |   |   | COR   | Dan   |  |
|  |   |   |   |   |  |
| cture<br>ardware   | -   | Awaiting Image                                |   |   |  |
| utputs   |   |   |   |   |  |
| otal number of high side switches  | 8   | 34  | 34  | 48  |  |
| ow Current High Side Switches umber of outputs   | 8   | 22  | 20  | 26  |  |
| laximum inrush current (A)   | 100   | 75  | 75  | 75  |  |
| laximum continuous current draw (A) ash function all outputs / Max frequency (Hz)            | 25<br>Yes / 300 Hz                            | 25<br>Yes / 300                               | 25<br>Yes / 300                               | 25<br>Yes / 300                               |  |
| ow Current PWM High/Low Side Switches  | 1es / 300 Hz                                  | 165 / 300                                     | 165 / 300                                     | 1es / 300                                     |  |
| umber of outputs   | -   | 2<br>75                                       | 2<br>75                                       | 4<br>75                                       |  |
| 1aximum inrush current (A)<br>1aximum continuous current draw (A)                            | -   | 25  | 25  | 25  |  |
| elect as low or high side output   | -   | Yes   | Yes   | Yes   |  |
| igital or frequency output ash function all outputs / Max frequency (kHz)                    | =   | Programmable<br>Yes / 25                      | Programmable<br>Yes / 25                      | Programmable<br>Yes / 25                      |  |
| ow Current High Side Wiper Switches  |   | 103 / 23                                      | 103 / 23                                      | 1637 23                                       |  |
| umber of outputs   | -   | 2   | 2   | 2   |  |
| Maximum inrush current (A) Maximum continuous current draw (A)                               | -<br>-  | 75<br>25                                      | 75<br>25                                      | 75<br>25                                      |  |
| elf parking wiper event  | -   | Yes   | Yes   | Yes   |  |
| ash function all outputs / Max frequency (Hz) igh Current High Side Switches                 | -   | Yes / 300                                     | Yes / 300                                     | Yes / 300                                     |  |
| umber of outputs   | -   | 8   | 8   | 12  |  |
| 1aximum inrush current (A) 1aximum continuous current draw (A)                               | ÷   | 100<br>50                                     | 100<br>50                                     | 100<br>50                                     |  |
| laximum continuous current draw (A) ash function all outputs / Max frequency (Hz)            | =   | 50<br>Yes / 300                               | 50<br>Yes / 300                               | 50<br>Yes / 300                               |  |
| ligh Current PWM High/Low Switches   |   |   |   |   |  |
| umber of outputs<br>faximum inrush current (A)   | <del>-</del>                                  | -   | 2<br>150                                      | 2<br>150                                      |  |
| Maximum continuous current draw (A)  | =   | -   | 50  | 50  |  |
| elect as low or high side output   | -   | -   | Yes   | Yes   |  |
| igital or frequency output ash function all outputs / Max frequency (kHz)                    | <del>-</del>                                  | -   | Programmable<br>Yes / 25                      | Programmable<br>Yes / 25                      |  |
| ery High Current High Side Switches  |   |   |   |   |  |
| umber of outputs<br>1aximum inrush current (A)   | -   | -   | -   | 2<br>150                                      |  |
| laximum continuous current draw (A)  | -   | -   | -   | 75  |  |
| ash function all outputs / Max frequency (Hz)  | -   | -   | -   | Yes / 300                                     |  |
| ri-State Triggers umber of outputs   | -   | -   | 4   | 4   |  |
| se as ECU trigger channels only / Max current (mA)   | -   | -   | Yes / 50                                      | Yes / 50                                      |  |
| utput status V Reference Voltage for Sensors   | -   | -   | 0V – 2.5V – 5V                                | 0V – 2.5V – 5V                                |  |
| lumber of stabilised VREF outputs  | 1   | 3   | 3   | 3   |  |
| Maximum current draw (mA)  | 500   | 100   | 1,000   | 1,000   |  |
| ault Warning Light and Reset xternal warning light for overload                              | Yes   | Yes   | Yes   | Yes   |  |
| se reset of channels in fault mode   | Yes   | Yes   | Yes   | Yes   |  |
| utomatic retry for output overload   | Yes   | Yes   | Yes   | Yes   |  |
| nalogue inputs   | 8   | 8   | 8   | 16  |  |
| ccuracy of analogue inputs, typical value<br>electable pull-up resistors on analogue inputs  | 1 mV<br>Fixed 47 kOhm                         | 1 mV<br>Fixed 47 kOhm                         | 1 mV<br>Yes / None – 3.16 – 47 kOhm           | 1 mV<br>Yes / None – 3.16 – 47 kOhm           |  |
| igital inputs  | 8<br>8  | 8 8   | 8 8   | 14  |  |
| rigger level for digital inputs  | Low – High – Open                             |  |
| dividual CAN ports / Terminate in software faximum number of CAN import addresses            | 2 / Yes<br>64                                 | 2 / Yes<br>64                                 | 4 / Yes<br>64                                 | 4 / Yes<br>64                                 |  |
| laximum number of CAN export addresses   | 64  | 64  | 64  | 64  |  |
| ommunication Interfaces AN   | Yes   | Yes   | Yes   | Yes   |  |
| SB   | Tes   | Yes   | -   | - Tes   |  |
| S232   | Yes   | Yes   | Yes   | Yes   |  |
| N<br>oftware   | -   | -   | Yes   | Yes   |  |
| ustom configurable control strategy  | User defined events                           | User defined events                           | User defined events                           | User defined events                           |  |
| equired software<br>nnual software license fee   | PCM2 Tool<br>No                               | PCM2 Tool<br>No                               | PCM2 Tool<br>No                               | PCM2 Tool<br>No                               |  |
| ommunication PC<→PCM   | CAN   | CAN / USB                                     | CAN   | CAN   |  |
| dvanced Software Strategies  | Low / Disk / C                                | Lou: /18-b / C                                | Loui / 1854 / C                               | Jam Just Jo                                   |  |
| onfiguration of digital triggers nalogue inputs pull-up resistors                            | Low / High / Open<br>None / 3.16 k / 47 k Ohm | Low / High / Open<br>None / 3.16 k / 47 k Ohm | Low / High / Open<br>None / 3.16 k / 47 k Ohm | Low / High / Open<br>None / 3.16 k / 47 k Ohm |  |
| nalogue input refresh rate (Hz)  | 100   | 100   | 100   | 100   |  |
| dividual scaling of analogue sensor values laximum CAN input channels                        | Yes<br>64                                     | Yes<br>64                                     | Yes<br>64                                     | Yes<br>64                                     |  |
| AN addresses limited   | Unlimited                                     | Unlimited                                     | Unlimited                                     | Unlimited                                     |  |
| AN messages and instructions as  | Bits / bytes / words                          |  |
| dividual scaling of CAN channels<br>dividual termination in software of CAN bus              | Yes<br>Yes                                    | Yes<br>Yes                                    | Yes<br>Yes                                    | Yes<br>Yes                                    |  |
| dividual CAN bus baud rates  | 10 kbits/s1 Mbit/s                            | 10 kbits/s1 Mbit/s                            | 10 kbits/s1 Mbit/s                            | 10 kbits/s1 Mbit/s                            |  |
| laximum CAN export channels AN routing possible  | 64<br>Yes                                     | 64<br>Yes                                     | 64<br>Yes                                     | 64<br>Yes                                     |  |
| AN bus monitor   | Yes   | Yes   | Yes   | Yes   |  |
| oftware fuse levels for outputs  | In steps of 1 mA                              | In steps of 1 mA<br>Yes, 2 levels             | In steps of 1 mA<br>Yes, 2 levels             | In steps of 1 mA<br>Yes, 2 levels             |  |
| dividual software settings for in-rush current<br>mer for overload detection for each output | Yes, 2 levels<br>Yes                          | Yes, 2 levels<br>Yes                          | Yes, 2 levels<br>Yes                          | Yes, 2 levels<br>Yes                          |  |
| utomatic reset of outputs in error status  | Yes   | Yes   | Yes   | Yes   |  |
| ser levels with individual password settings<br>pecial function ON for any selected event    | 5<br>Yes                                      | 5<br>Yes                                      | 5<br>Yes                                      | 5<br>Yes                                      |  |
| pecial function OFF for any selected event   | Yes   | Yes   | Yes   | Yes   |  |
|  | Yes   | Yes   | Yes   | Yes   |  |
| counter function   |   | Ontional                                      |   |   |  |
| eal time clock tatus and diagnostic data for inputs and outputs                              | -<br>Yes                                      | Optional<br>Yes                               | Yes<br>Yes                                    | Yes<br>Yes                                    |  |
| eal time clock   |   |   |   |   |  |
| eal time clock   |   |   |   |   |  |





### A new horizon in power management

OBR's PCM2\_AC thrusts the concept of intelligent power management to new pinnacles. It provides a freely programmable, open and unique system upon which to build total control of a racing car's electrical system.

Based on the competitive success, knowledge and experience gleaned from OBR's PCM2, PCM2\_AC is the most technologically advanced, powerful and flexible unit ever seen in this compact measure.

PCM2\_AC has unrivalled high current handling and measuring abilities spread across its 8 individual power output channels, each of which can be controlled by any number and type of input or trigger. All power outputs have self-recovery features suitable for use with motors and resistive and inductive loads. Outputs handle peak currents up to 75A.

The PCM2\_AC effortlessly exchanges data with other modules in the car primarily over its multiple CAN ports. This means that every value and data packet that is exchanged, recorded or seen e.g. current draw and channel status can be exported and shared over all of the PCM2\_AC open CAN network. The PCM2\_AC also supports CAN routing meaning data can be exchanged from one bus to another bus freely, exported to wherever the user defines.

All CAN data channels are completely free for the user to configure, there are no limitations to CAN address or how the protocol is configured. The PCM2\_AC will therefore interface easily with any other CAN based product found on the market.

In addition to the free CAN structure, the PCM2\_AC has 8 analogue sensor inputs and 8 digital inputs. Analogue inputs can be paired individually to become differential inputs.

PCM2\_AC is also equipped with a real time clock and data recording capabilities.

### Software

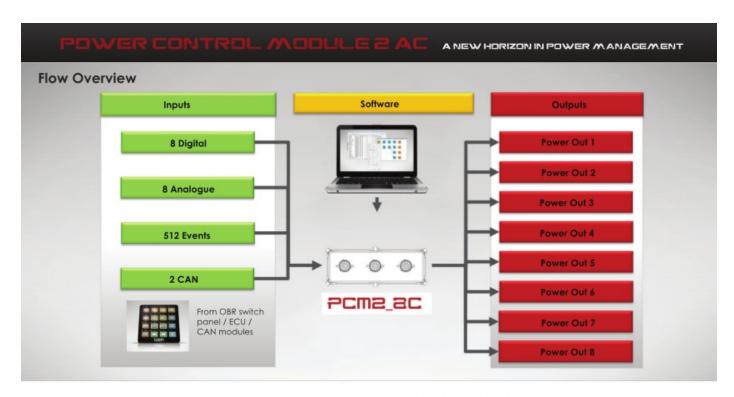
The PC Tool used to configure the PCM2\_AC has been logically laid out and is simple to use.

A special feature of the PC Tool is the graphic visualizer which makes calibration, modification and fault finding of the unit's configuration near to effortless.

### **Event based handling**

PCM2\_AC is controlled by configurable software events. Events are used to define and create specific conditions, simple as well as complex, which then controls an output or other events. Multiple events can be placed within other events, creating almost unlimited control conditions.





### **General Specifications**

- 8 Power outputs
- 8 Digital inputs
- · 8 Analogue sensor inputs
- 64 Individually programmable CAN inputs, 11 or 29 bit identifiers, with bit operator
- 2 Individually programmable CAN bus with No limitation on CAN id's
- RS232 Link
- VREF sensor supply
- Fault warning light
- CNC machined and anodized enclosure (O-ring sealed)
- Deutsch Autosport connectors

### **Electrical Specifications**

- Supply voltage 6 to 30 volts
- Maximum operating temperature ≤85 °C
- Maximum recommended continuous output current 100A
- In-rush current capability 500A

### **Software Specifications**

- 512 individually programmable events
- Automatic and user-defined pre-set channel shutdown protection
- Programmable inrush current levels and inrush times
- Programmable fuse thresholds, retries and retry time intervals
- Manuel reset function for all overloaded channels
- Current draw and channel status diagnostics
- Compatible with OBR's range of membrane switch panels (software selectable)





### A new horizon in power management

OBR's Power Control Module 2 thrusts the concept of intelligent power management to new pinnacles. It provides a freely programmable, open and unique system upon which to build total control of a racing car's electrical system.

Based on the competitive success, knowledge and experience gleaned from OBR's first PCM incarnation, PCM2 is the most technologically advanced, powerful and flexible unit ever seen. It acts as a complete electronic central nervous system.

PCM2 has unrivalled high current handling and measuring abilities spread across its 48 individual power output channels, each of which can be controlled by any number and type of input or trigger. All power outputs have self-recovery features suitable for use with motors and resistive and inductive loads. Some outputs handle peak currents in excess of 300A.

The PCM2 effortlessly exchanges data with other modules in the car primarily over its multiple CAN ports. This means that every value and data packet that is exchanged, recorded or seen e.g. current draw and channel status can be exported and shared over all of the PCM2's open CAN network. The PCM2 also supports CAN routing meaning data can be exchanged from one bus to another bus freely, exported to wherever the user defines.

All CAN data channels are completely free for the user to configure, there are no limitations to CAN address or how the protocol is configured. The PCM2 will therefore interface easily with any other CAN based product found on the market.

In addition to the free CAN structure, the PCM2 has 16 analogue sensor inputs and 14 digital inputs. Analogue inputs can be paired individually to become differential inputs.

PCM2 is also equipped with a real time clock and data recording capabilities.

### Software

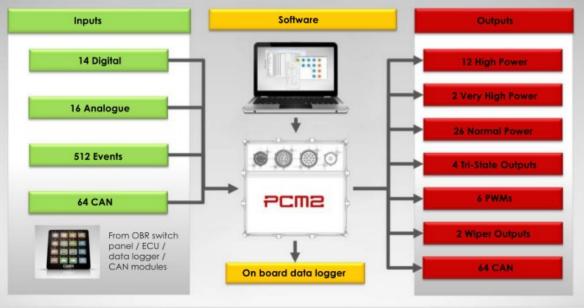
The PC Tool used to configure the PCM2 has been logically laid out and is simple to use.

A special feature of the PC Tool is the graphic visualizer which makes calibration, modification and fault finding of the unit's configuration near to effortless.

### **Event based handling**

PCM2 is controlled by configurable software events. Events are used to define and create specific conditions, simple as well as complex, which then controls an output or other events. Multiple events can be placed within other events, creating almost unlimited control conditions.

### Flow Overview



### **General Specifications**

- 48 Power outputs
- 14 Digital inputs
- 16 Analogue sensor inputs
- 64 Individually programmable CAN inputs, 11 or 29 bit identifiers, with bit operator
- 4 Individually programmable CAN bus with No limitation on CAN id's
- 1 LIN Bus
- Ethernet Connection
- Real Time Clock
- RS232 Link
- 4 Tri-state outputs (a tri-state output is only for use as an ECU trigger)
- 3 VREF sensor supplies
- Fault warning light
- CNC machined and anodized enclosure (O-ring sealed)
- Deutsch Autosport connectors
- Weight 1190 grams

### **Electrical Specifications**

- Supply voltage 6 to 30 volts
- Maximum operating temperature ≤85 °C
- Typical temperature rise over ambient <25°C @ 140A; 30 minutes
- Maximum recommended continuous output current 300A
- In-rush current capability 1000A

### **Software Specifications**

- · 512 individually programmable events
- Automatic and user-defined pre-set channel shutdown protection
- Programmable inrush current levels and inrush times
- Programmable fuse thresholds, retries and retry time intervals
- · Manuel reset function for all overloaded channels
- Current draw and channel status diagnostics
- Compatible with OBR's range of membrane switch panels (software selectable)

